## **Highly Scalable Parallel Sorting**

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# Outline

- Parallel sorting background
- Histogram Sort overview
- Histogram Sort optimizations
- Results
- Limitations of work
- Contributions
- Future work

# **Parallel Sorting**

- Input
  - There are <u>n</u> unsorted keys, distributed evenly over <u>p</u> processors
  - The distribution of keys in the range is unknown and possibly skewed
- Goal
  - Sort the data globally according to keys
  - Ensure no processor has more than (n/p)+threshold keys

# **Scaling Challenges**

- Load balance
  - Main objective of most parallel sorting algorithms
  - Each processor needs a continuous chunk of data

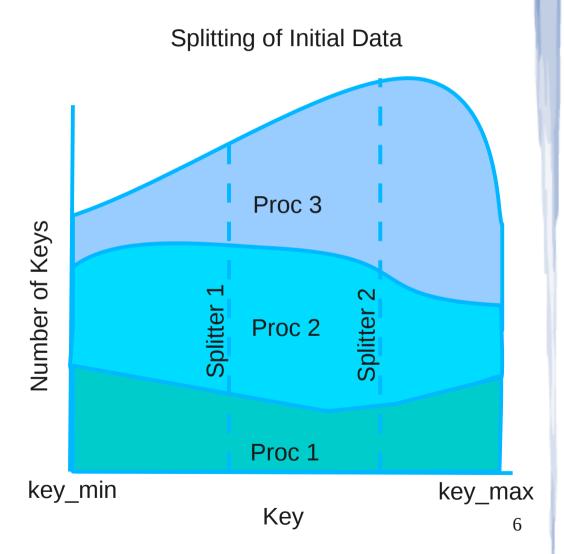
- Data exchange communication
  - Can require complete communication graph
  - All-to-all contains n elements in  $p^2$  messages

## Parallel Sorting Algorithms

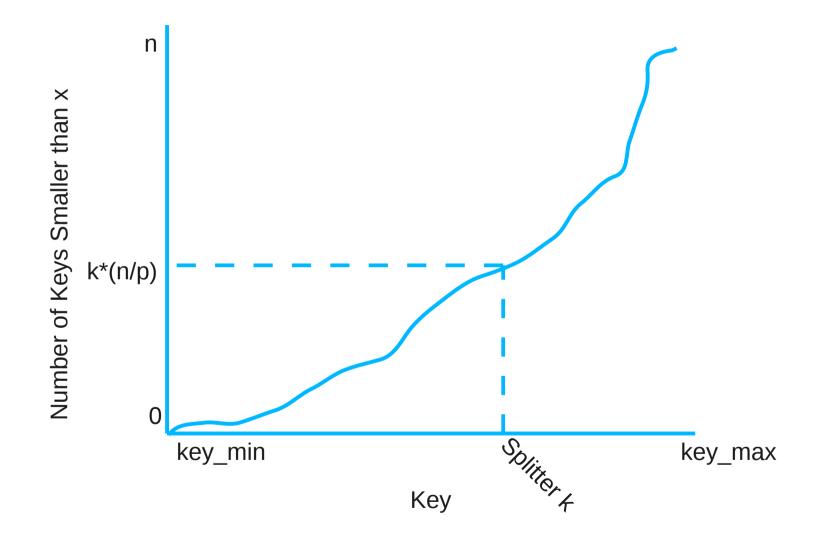
Туре	Data movement
<ul> <li>Merge-based</li> </ul>	
<ul> <li>Bitonic Sort</li> </ul>	<sup>1</sup> /2*n*log² <b>(p)</b>
<ul> <li>Cole's Merge Sort</li> </ul>	O(n*log(p))
<ul> <li>Splitter-based</li> </ul>	
-	
<ul> <li>Sample Sort</li> </ul>	n
– Sample Sort – <b>Histogram Sort</b>	n n
– Histogram Sort	

#### **Splitter-Based Parallel Sorting**

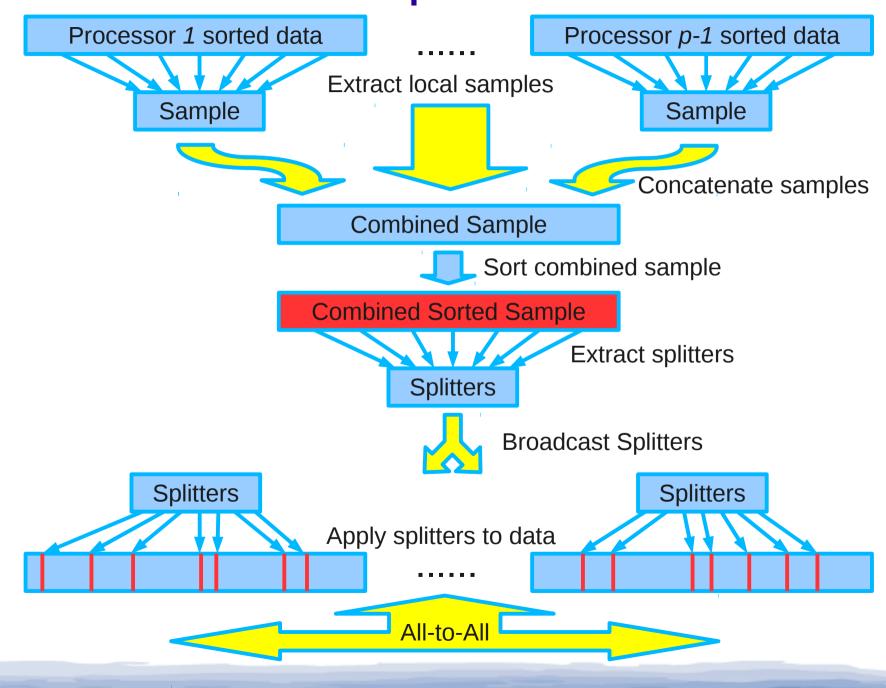
- A *splitter* is a key that partitions the global set of keys at a desired location
- *p-1* global splitters needed to subdivide the data into *p* continuous chunks
- Each processor can send out its local data based on the splitters
  - Data moves only once
- Each processor merges the data chunks as it receives them



#### Splitter on Key Density Function



## Sample Sort

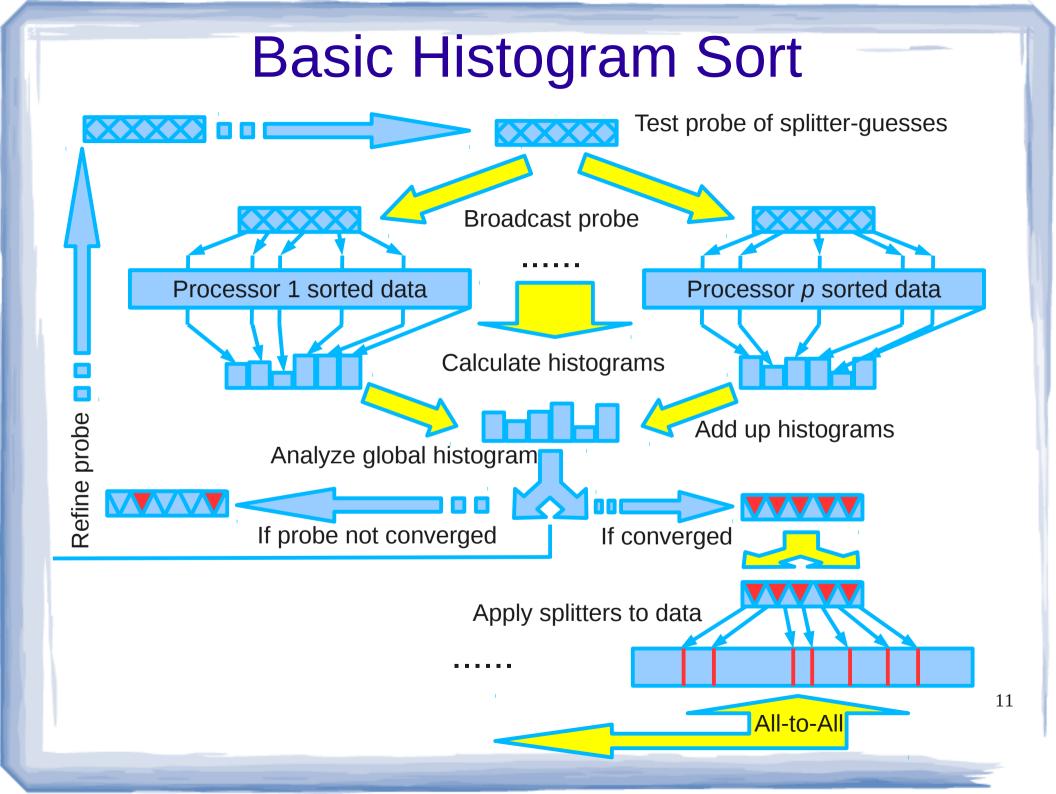


### Sample Sort

- The sample is typically regularly spaced in the local sorted data s=p-1
  - Worst case final load imbalance is **2\*(n/p)** keys
  - In practice, load imbalance is typically very small
- Combined sample becomes bottleneck since (s\*p)~p<sup>2</sup>
  - With 64-bit keys, if *p* = **8192**, sample is **16 GB**!

## **Basic Histogram Sort**

- Splitter-based
- Uses iterative guessing to find splitters
  - O(p) probe rather than O(p<sup>2</sup>) combined sample
  - Probe refinement based on global histogram
    - Histogram calculated by applying splitters to data
- Kale and Krishnan, ICPP 1993
- Basis for this work



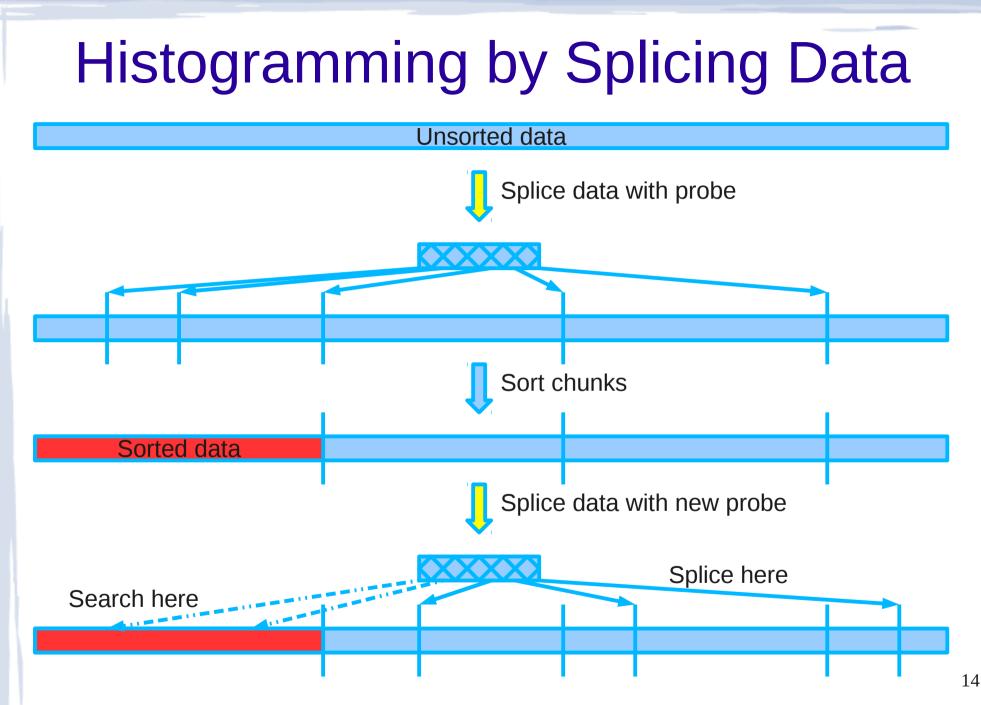
## **Basic Histogram Sort**

#### Positives

- Splitter-based: single all-to-all data transpose
- Can achieve arbitrarily small threshold
- Probing technique is scalable compared to sample sort, O(p) vs O(p<sup>2</sup>)
- Allows good overlap between communication and computation (to be shown)
- Negatives
  - Harder to implement
  - Running time dependent on data distribution

# Sorting and Histogramming Overlap

- Don't actually need to sort local data first
- Splice data instead
  - Use splitter-guesses as Quicksort pivots
  - Each splice determines location of a guess and partitions data
- Sort chunks of data while histogramming happens



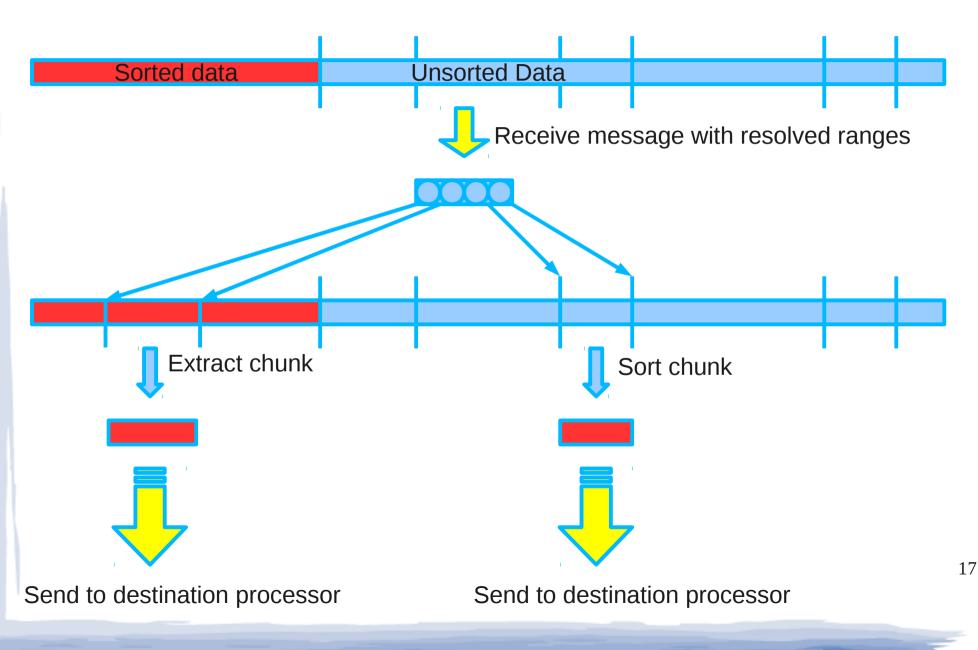
## Histogram Overlap Analysis

- Probe generation work should be offloaded to one processor
  - Reduces critical path
- Splicing is somewhat expensive
  - O((n/p)\*log(p)) for first iteration
    - *log(p)* approaches *log(n/p)* in weak scaling
  - Small theoretical overhead (limited pivot selection)
  - Slight implementation overhead (libraries faster)
  - Some optimizations/code necessary

#### Sorting and All-to-All Overlap

- Histogram and local sort overlap is good but the all-to-all is the worst scaling bottleneck
- Fortunately, much all-to-all overlap available
- All-to-all can initially overlap with local sorting
  - Some splitters converge every histogram iteration
    - This is also prior to completion of local sorting
    - Can begin sending to any defined ranges

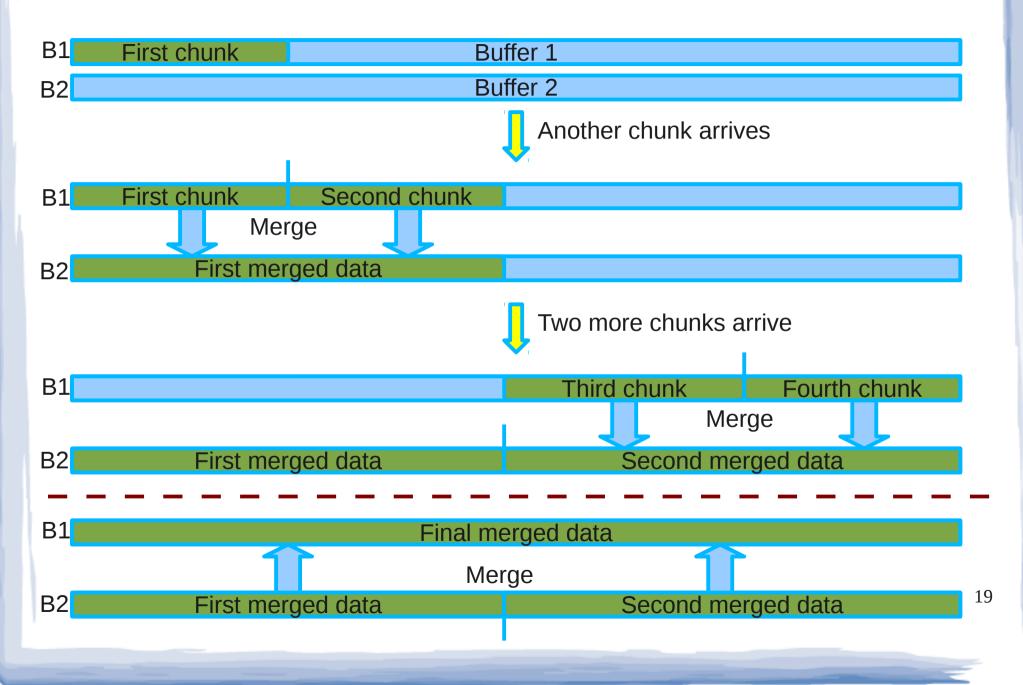
## Eager Data Movement



## All-to-All and Merge Overlap

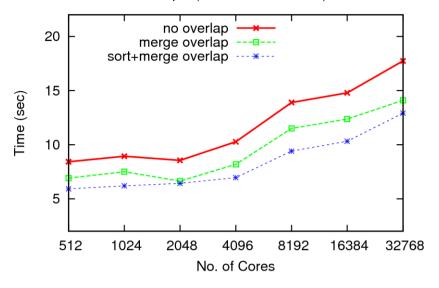
- The k-way merge done when the data arrives should be implemented as a tree merge
  - A k-way heap merge requires all k arrays
  - A tree merge can start with just two arrays
- Some data arrives much earlier than the rest
  - Tree merge allows overlap

## **Tree k-way Merging**

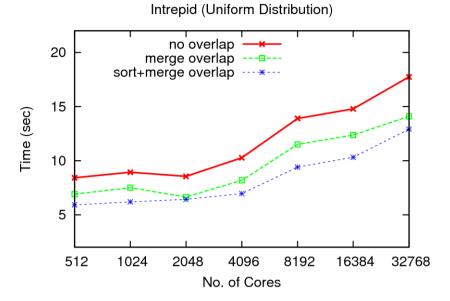


#### **Overlap Benefit (Weak Scaling)**

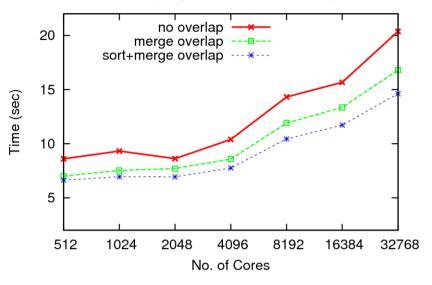
Intrepid (Uniform Distribution)



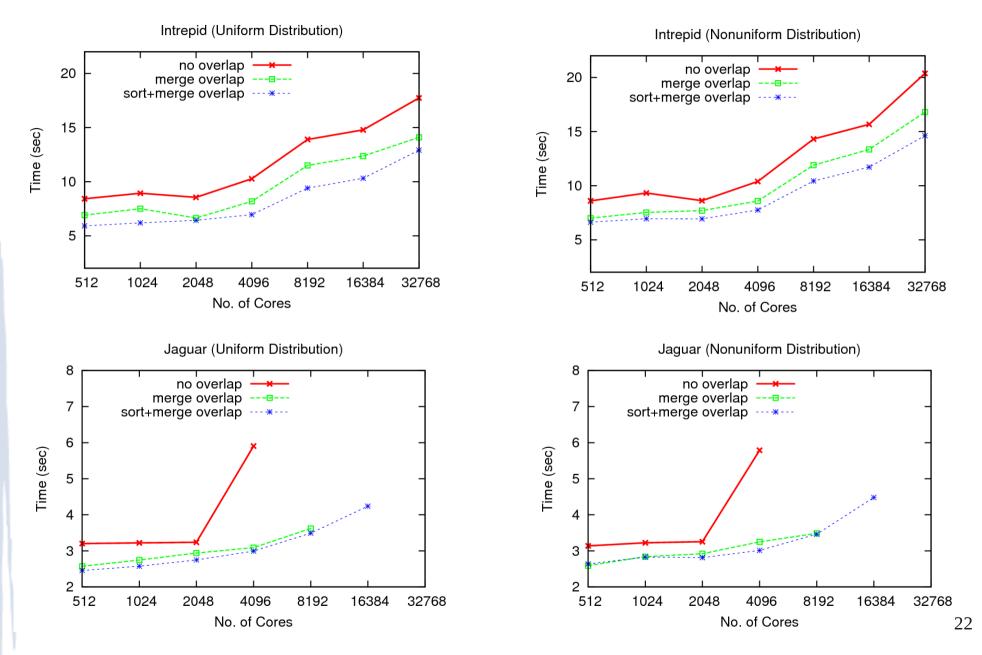
#### **Overlap Benefit (Weak Scaling)**



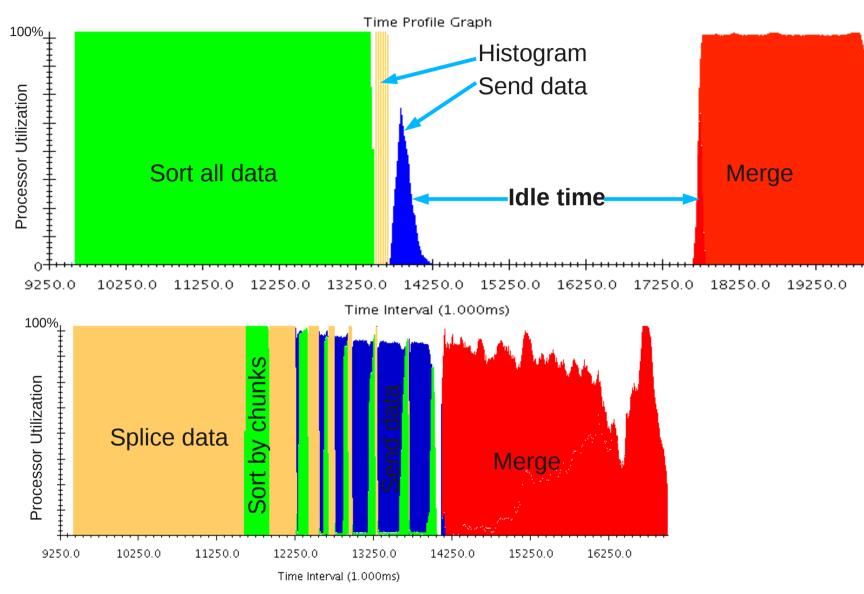
Intrepid (Nonuniform Distribution)



#### **Overlap Benefit (Weak Scaling)**



#### Effect of All-to-All Overlap

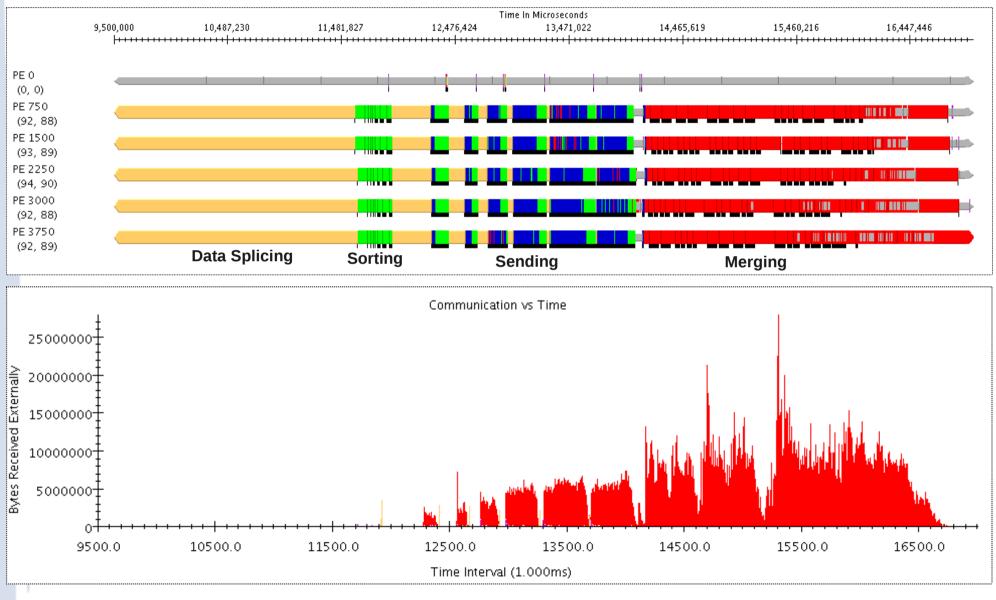


Tests done on 4096 cores of Intrepid (BG/P) with 8 million 64-bit keys per core.

## All-to-All Spread and Staging

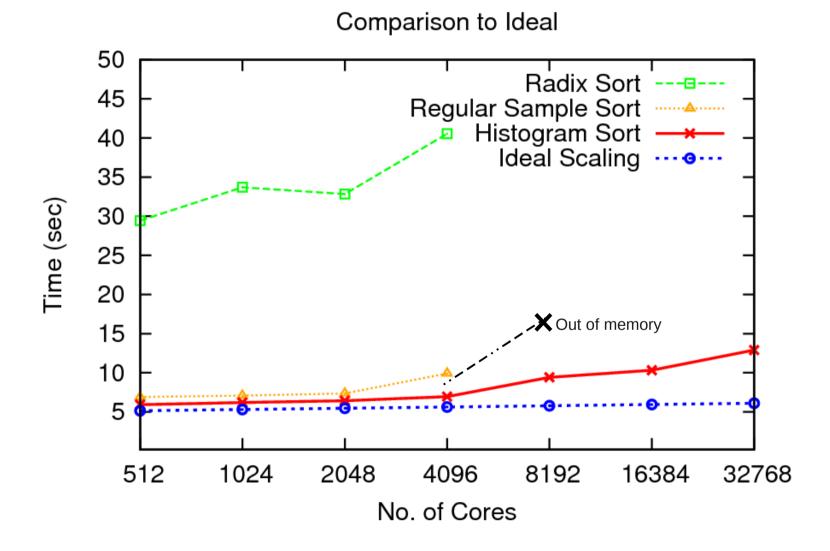
- Personalized all-to-all collective communication strategies important
  - All-to-all eventually dominates execution time
- Some basic optimizations easily applied
  - Varying order sends
    - Minimizes network contention
  - Only a subset of processors should send data to one destination at a time
    - Prevents network overload

#### **Communication Spread**



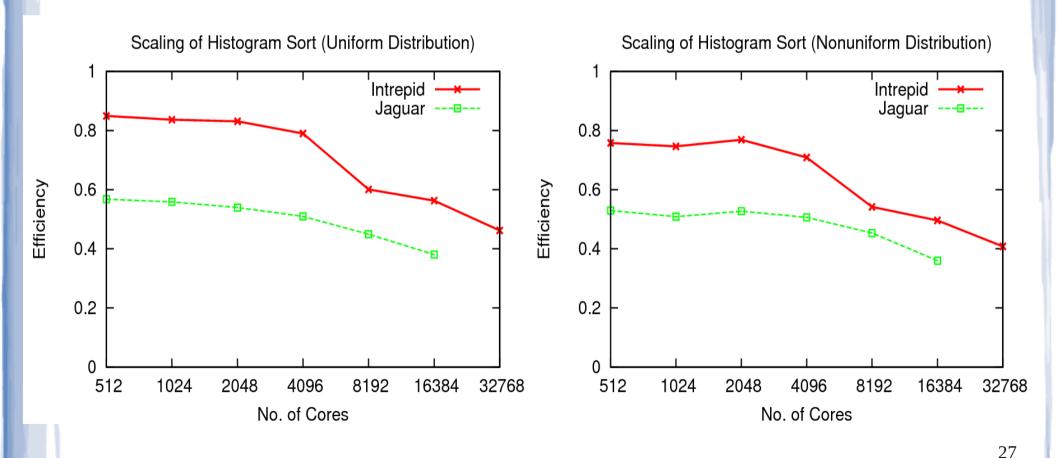
Tests done on 4096 cores of Intrepid (BG/P) with 8 million 64-bit keys per core.

## **Algorithm Scaling Comparison**



Tests done on Intrepid (BG/P) with 8 million 64-bit keys per core.

#### **Histogram Sort Parallel Efficiency**



## Some Limitations of this Work

- Benchmarking done with 64-bit keys rather than key-value pairs
- Optimizations presented are only beneficial for certain parallel sorting problems
  - Generally, we assumed  $n > p^2$ 
    - Splicing useless unless n/p > p
    - Different all-to-all optimizations required if *n/p* is small (combine messages)
  - Communication usually cheap until *p*>512
- Complex implementation another issue

# Future/Ongoing Work

- Write a further optimized library implementation of Histogram Sort
  - Sort key-value pairs
  - Almost completed, code to be released
- To scale past 32k cores, histogramming needs to be better optimized
  - As  $p \rightarrow n/p$ , probe creation cost matches the cost of local sorting and merging
  - One promising solution is to parallelize probing
    - Can use early determined splitters to divide probing

# Contributions

- Improvements on original Histogram Sort algorithm
  - Overlap between computation and communication
  - Interleaved algorithm stages
- Efficient and well-optimized implementation
- Scalability up to tens of thousands of cores
- Ground work for further parallel scaling of sorting algorithms

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