

Application Performance Analysis on Petascale Systems

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German Research School for Simulation Sciences

- Joint venture between
 - Forschungszentrum Jülich
 - RWTH Aachen University
- Founded in 2007
- Research and education in simulation sciences
 - International Master's program
 - Ph.D. program



RWTHAACHEN UNIVERSITY





Jülich Supercomputing Centre



Research in

- Computational Science
- Computer Science
- Mathematics



Jülich BG/P 294,912 cores



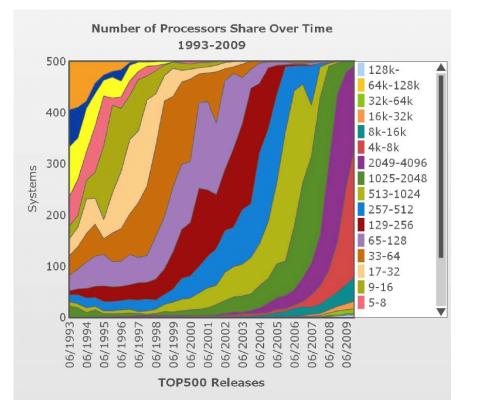
Jülich Nehalem Cluster 26,304 cores

Outline

- Motivation
- Scalasca overview
- Scalable trace analysis
- Scalable task-local I/O
- Space-efficient time-series call-path profiles
- Conclusion & outlook

Higher degrees of parallelism

- Increasing complexity of applications
 - Higher resolutions
 - Larger simulated time periods
 - Multi-physics
 - Multi-scale
- Increasing parallelism
 - Multi-core



Higher degrees of parallelism (2)

- Also new demands on scalability of software tools
 - Familiar tools cease to work in a satisfactory manner for large processor counts
- Optimization of applications more difficult
 - Increasing machine complexity
 - Every doubling of scale reveals a new bottleneck
- Need for scalable performance tools
 - Intelligent
 - Robust
 - Easy to use

scalasca 🗖

- Scalable performance-analysis toolset for parallel codes
- Integrated performance analysis process
 - Performance overview on call-path level via runtime summarization
 - In-depth study of application behavior via event tracing
 - Switching between both options without recompilation or relinking
- Supported programming models
 - MPI-1, MPI-2 one-sided communication
 - OpenMP (basic features)
 - Available under the New BSD open-source license
 - http://www.scalasca.org/

Joint project of



Scalasca team





















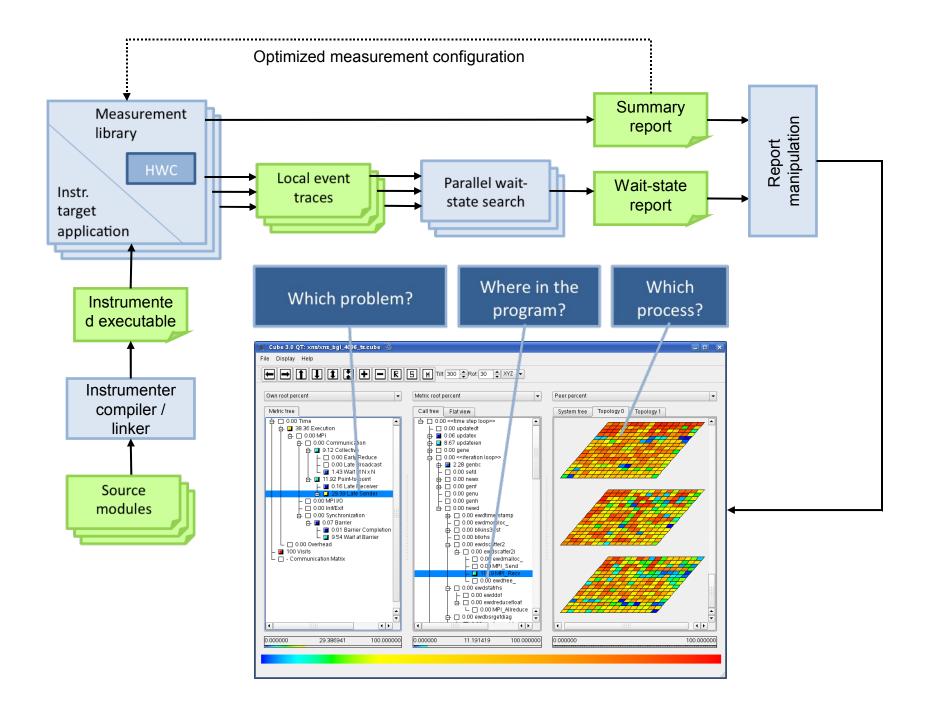




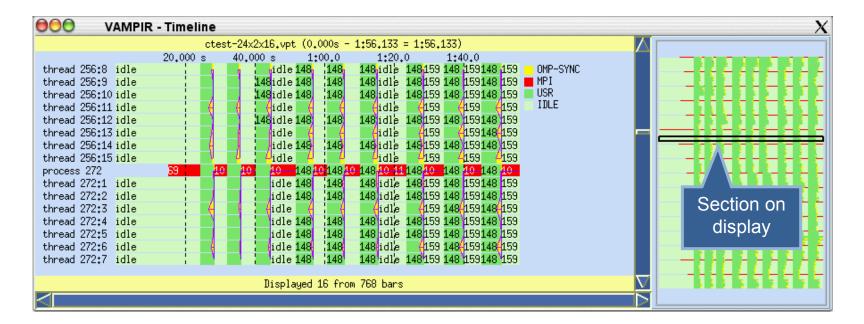








Event tracing



- Typical events
 - Entering and leaving a function
 - Sending and receiving a message
- Problem: width and length of event trace

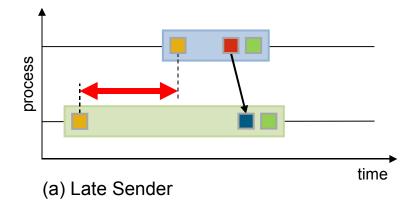
Scalable trace analysis via parallel replay

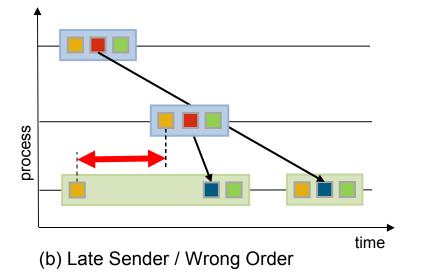
- Exploit distributed memory and processing capabilities
 - Keep trace data in main memory
 - Traverse local traces in parallel
 - Exchange data at synchronization points of target application using communication operation of similar type
- Four applications

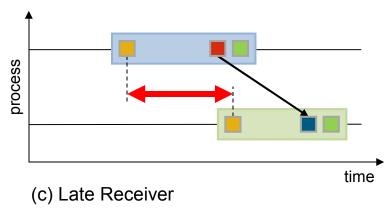
Wait-state analysis	Delay analysis	Synchronization of timestamps	Evaluation of optimization hypotheses
	Paralle	l replay	

Wait-state analysis

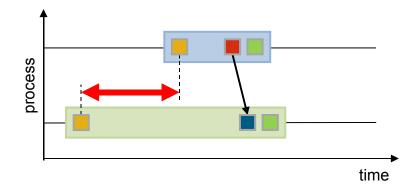
- Classification
- Quantification



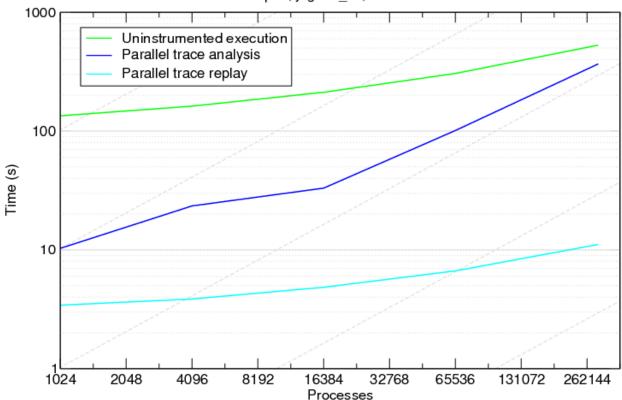




Wait-state analysis (2)

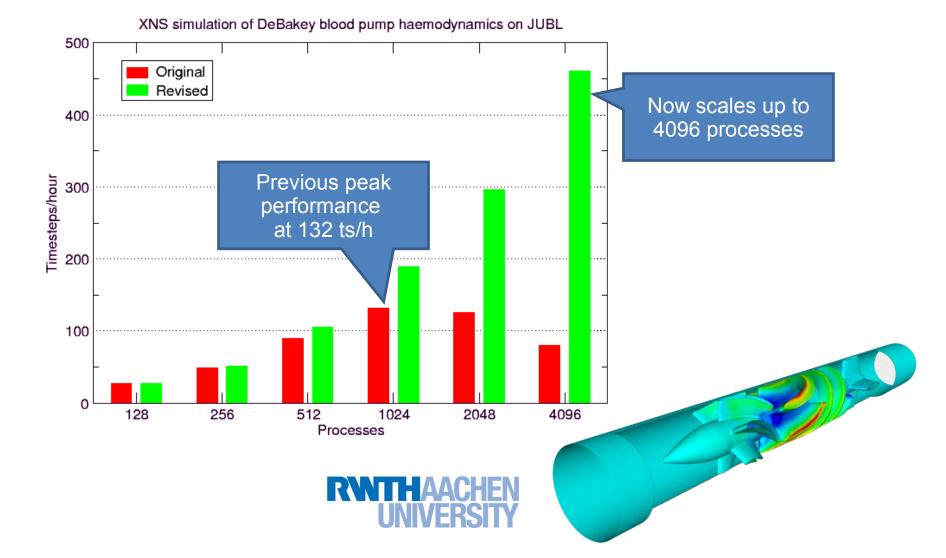


Scalability of parallel wait-state search (SWEEP3D)

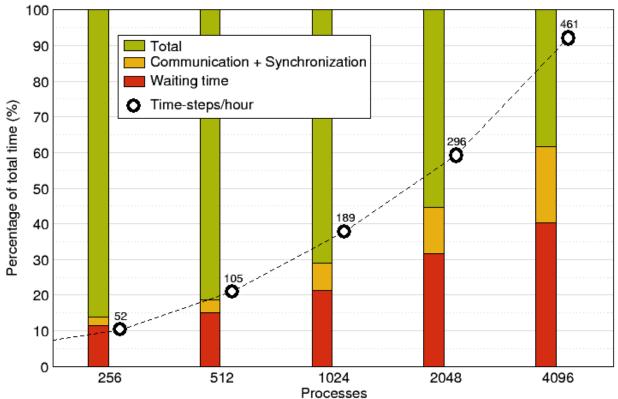


sweep3d, jugene_vn, scalasca-1.2

Redundant messages in XNS CFD code



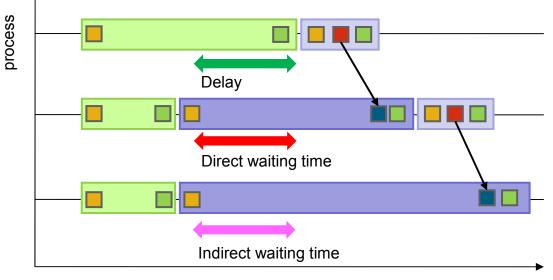
XNS wait-state analysis of tuned version



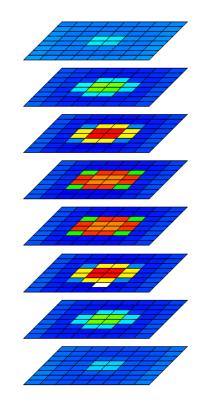
(tuned version, simulation time-step loop)

Delay analysis

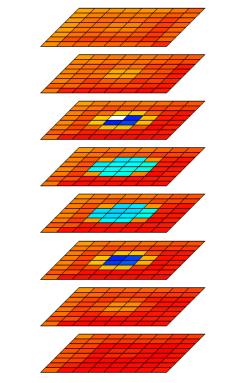
- Delay counterpart of waiting time
- Distinction between direct and indirect waiting times
- Essentially scalable version of Meira Jr. et al.
- Analysis attributes costs of wait states to delay intervals



Origin of delay costs in Zeus-MP/2



Computation

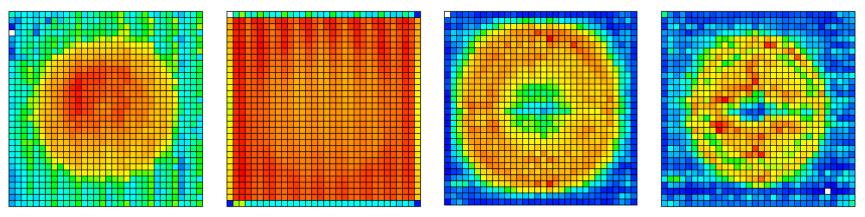




Delay costs

Delay analysis of code Illumination

- Particle physics code (laser-plasma interaction)
- Delay analysis identified inefficient communication behavior as cause of wait states

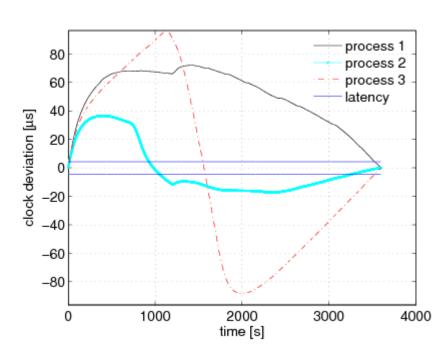


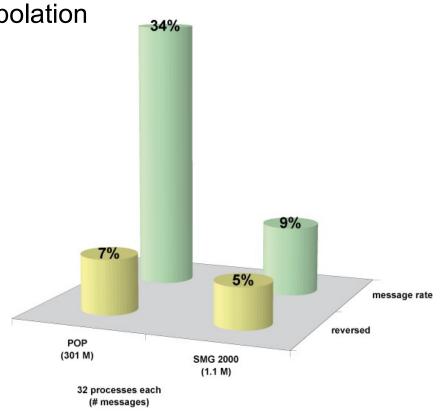
Computation

Short-term costs of indirect delay: Original vs. optimized code Costs of direct delay in optimized code

Insufficiently synchronized clocks on clusters

- Misrepresentation of logical event order in traces
- Distorted interval lengths
- Simple approach: linear offset interpolation
- Problem unstable drifts





Postmortem correction using logical clocks

- Controlled logical clock algorithm by Rolf Rabenseifner
 - Restores logical event order based on happened-before relation while introducing only marginal local inaccuracies
 - Shortcoming 1: Only point-to-point communication
 - Shortcoming 2: Sequential algorithm
- Extended to cover MPI collective communication and OpenMP shared-memory programming
 - Mapped collectives and OpenMP regions onto point-to-point messages
- Parallelized through parallel replay
 - Challenge: backward replay required to smooth jump discontinuities without introducing new violations
 - Scalability tested on up to 4,000 processors



Evaluation of optimization hypotheses

- Wait states often caused by load or communication imbalance occurring much earlier in the program
 - Hard to estimate impact of potential changes
 - Requires modeling the communication infrastructure to answer "What if...?" questions
- Alternative
 - Parallel real-time replay of modified event traces to verify hypotheses on wait state formation
 - Elapse computation time
 - Re-enact communication
 - Advantage: scalability and accuracy

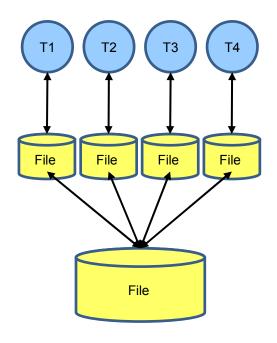
Simulated removal of redundant messages

- 1 iteration of 1024 processor-run of XNS on Blue Gene/L
- All zero-sized messages removed from trace
 - 90% of all messages > 1.2 billion messages

Metric	Original	Hand- Optimized	Simulated
Total	100.0	50.6	53.1
MPI	59.9	16.9	19.4
P2P	54.2	8.6	11.2
Late Sender	30.6	5.7	8.0
Wait at Barrier	5.1	7.7	7.7

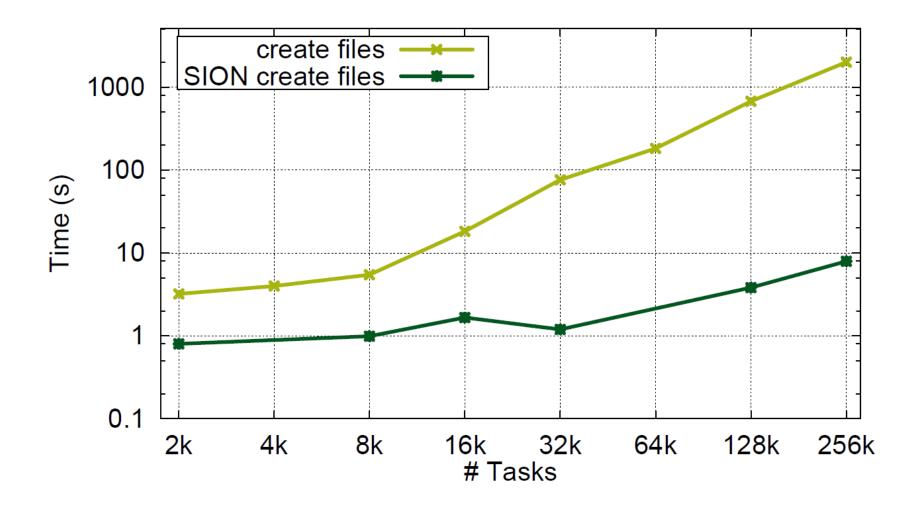
SIONlib: Scalable parallel I/O for task-local data

- Use case: task-local binary I/O from thousands of tasks
 - Trace files
 - Scratch/checkpoint files
- Often does not scale
 - Contention at metadata server
 - File handling (e.g., directory listing)
- Map many logical files onto a few physical files
 - Application-level file system
 - Optimized I/O via block alignment

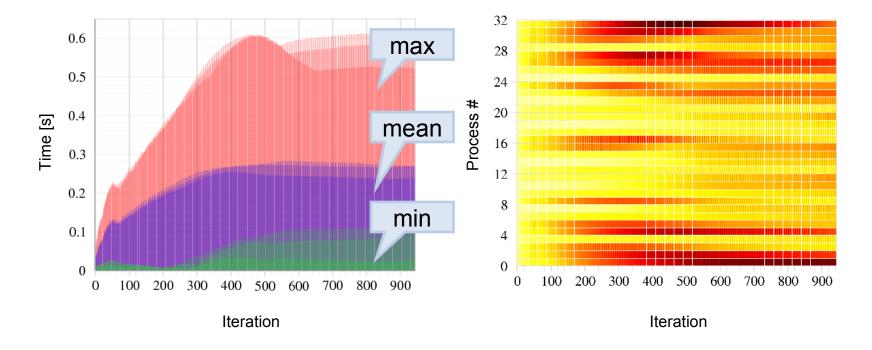




Parallel open / create on JUGENE



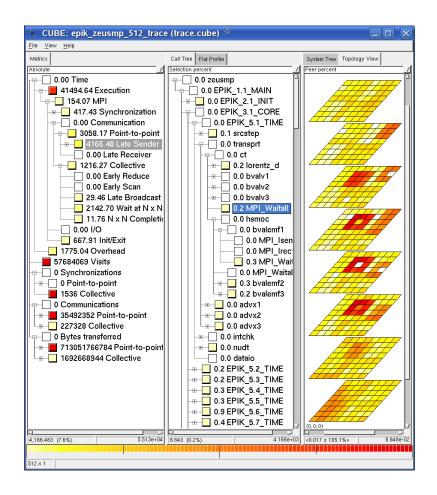
Time-dependent performance behavior



MPI point-to-point time of 129.tera_tf

Time-series call-path profiling

- Manual instrumentation to distinguish iterations of the main loop
- Complete call-tree recorded for each iteration
 - With multiple metrics collected for every call-path
- Huge growth in the amount of data collected
 - Reduced scalability

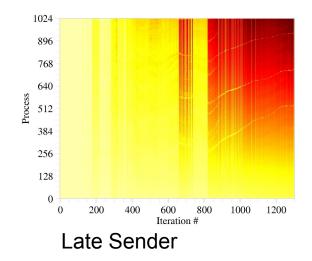


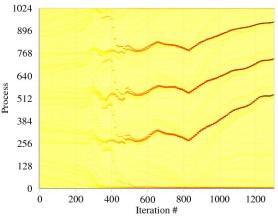
Incremental on-line clustering

- Exploits that many iterations are very similar
 - Summarizes similar iterations in a single iteration, their average
- On-line to save memory at run-time
- Process-local to
 - Avoid communication
 - Adjust to local temporal patterns
- The number of clusters can never exceed a predefined maximum
 - Merging of the two closest ones



PEPC n-body tree code

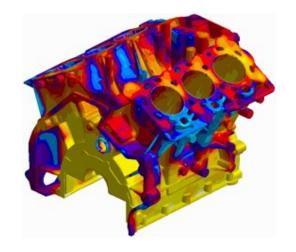


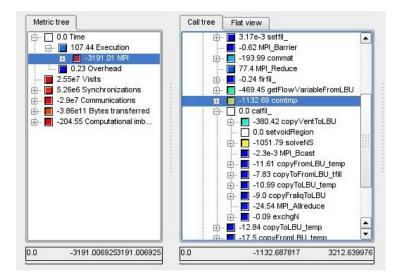


particles owned by a process

MAGMAfill by MAGMASOFT® GmbH

- Simulates mold-filling in casting processes
- Scalasca used
 - To identify communication bottleneck
 - To compare alternatives using performance algebra utility
- 23% overall runtime improvement
- Further investigations ongoing





Conclusion

- Integrated tool architecture
- Scalability in terms of machine size
 - Trace-processing based on parallel replay
 - Versatile: four applications
 - Parallel task-local I/O
 - Demonstrated on up to 295 K cores
- Scalability in terms of execution time
 - Runtime compression of time-series profiles

Outlook

- Further scalability improvements
 - Parallelization of internal management operations
 - Scalabale output format and GUI
 - In-memory trace analysis
- Emerging architectures and programming models
 - PGAS languages
 - Accelerator architectures
- Interoperability with 3rd-party tools
 - Common measurement library for several performance tools

Thank you!

DFG



Deutsche Forschungsgemeinschaft



Bundesministerium für Bildung und Forschung



Sweep3D – late sender

	Absolute - P	Peer distribution	
etric tree	Call tree Flat view	System tree Topology 0 Topology 1	
 ○.00 Time ○.00 MPI ○.00 MPI ○.00 Communication ○.00 Early Reduce ○.00 Early Reduce ○.00 Early Scan ○.00 Early Scan ○.00 File l/O ○.00 File l/O<!--</th--><th> □ 0.00 task_init □ 0.00 read_input □ 0.00 decomp □ 0.00 inner_auto □ 0.00 inner □ 0.00 initialize □ 0.00 barrier_sync □ 0.00 timers □ 9167.53 [its=1] □ 8689.45 [its=2] □ 8669.55 [its=4] □ 8809.96 [its=6] □ 8519.58 [its=7] □ 25399.20 [its=8] □ 27369.79 [its=9] □ 27869.31 [its=11] □ 27673.57 [its=12] □ 0.00 global_real_sum □ 0.00 task_end </th><th></th><th></th>	 □ 0.00 task_init □ 0.00 read_input □ 0.00 decomp □ 0.00 inner_auto □ 0.00 inner □ 0.00 initialize □ 0.00 barrier_sync □ 0.00 timers □ 9167.53 [its=1] □ 8689.45 [its=2] □ 8669.55 [its=4] □ 8809.96 [its=6] □ 8519.58 [its=7] □ 25399.20 [its=8] □ 27369.79 [its=9] □ 27869.31 [its=11] □ 27673.57 [its=12] □ 0.00 global_real_sum □ 0.00 task_end 		

Sweep3D – execution time

