

High performance Peer to Peer Distributed Computing with Application to Obstacle Problem

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Outline

- 1 **Goal**
- 2 **Self-adaptive protocol**
- 3 **Environment**
- 4 **Experiments**
- 5 **Conclusions**

1. Goal

- Great development of peer to peer applications
 - File sharing, video, ...
 - Recent advances in microprocessor architecture and high bandwidth network → new applications like distributed HPC computing/computing on the Internet.

- Great challenges
 - Scalability,
 - Heterogeneity,
 - Volatility,
 - Existing protocols, TCP, UDP not well suited to HPC.



1. Goal (cont'd)

- High performance peer to peer computing:
 - Task parallel model, distributed iterative methods.
 - Direct communications between peers.
 - Applications: numerical simulation & optimization.

- Self-adaptive protocol:
 - based on Cactus framework
 - uses micro-protocols
 - chooses dynamically the most appropriate communication mode in function of elements of context from network level and choices at application level.



2. Self-adaptive protocol

□ Micro-protocols

- Introduced in x-kernel
- Approach to design self-adaptive communication protocols

□ Micro-protocols implement a functionality (sample)

- Communication: Synchronous, Asynchronous.
- Fragmentation: FixeSize, Resize.
- Reliability: Retransmission, PositiveAck, NegativeAck, DuplicateAck.
- Order : LossyFifo, ReliableFifo.
- Congestion control: NewReno TCP Congestion Control.

□ Composition of micro-protocols → protocol

- Reuse code, facilitate design, configure dynamically.



2. Self-adaptive protocol (cont'd)

□ Protocol composition framework → deployment of architecture

- Hierarchical model (stack of protocols), **x-kernel**, **APPIA** frameworks.
- Nonhierarchical model (no order), **Coyote** and **ADAPTIVE** frame'ks.
- Hybrid model (combo), **XQoS** and **Cactus** frameworks → CTP.

□ Cactus framework

- flexible, efficient.
- Two grain levels:
 - Composite protocols : individual protocol made of micro-protocols.
 - Protocol stack : composite protocols layered on the top of each others.
- Protocols can reconfigure by substituting protocols or micro-protocols.



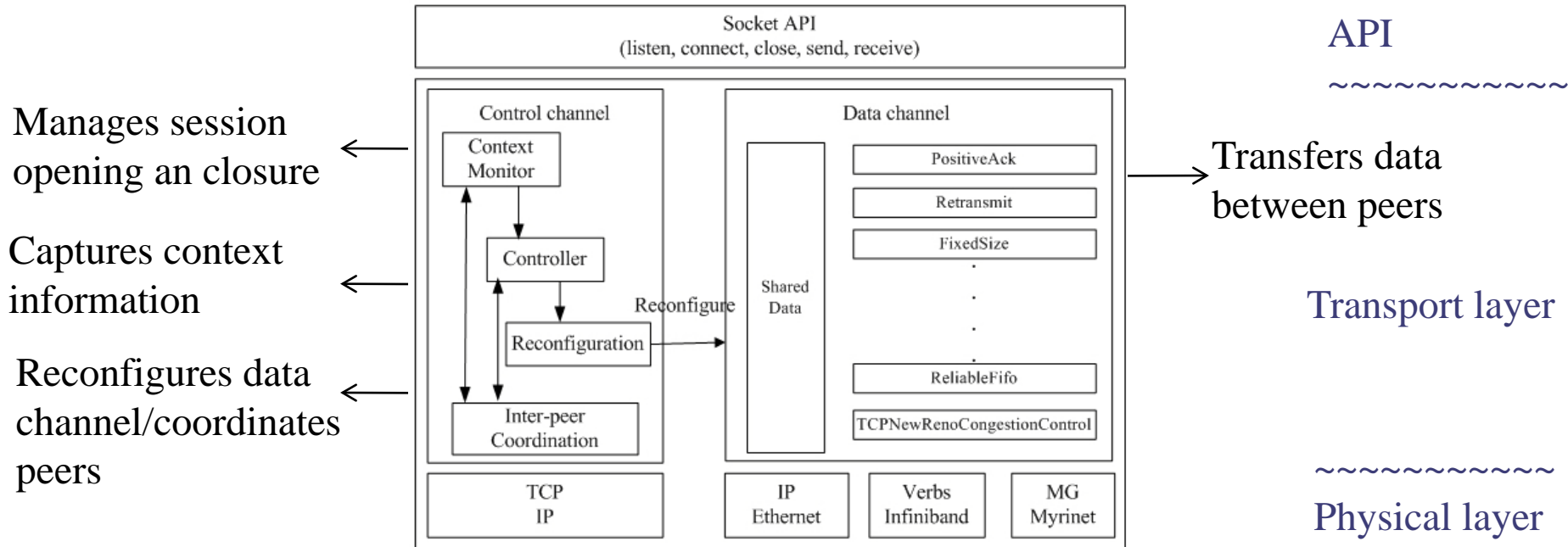
2. Self-adaptive protocol (cont'd)

- ❑ Cactus is an event based framework:
 - Events: state changes, e.g. arrival of messages.
- ❑ Micro-protocols structured as a collection of event handlers:
 - Event handler : procedure like segments of codes bound to events.
 - When an event occurs all handlers bound to that event are executed.
- ❑ Our modifications to Cactus → improve protocol performance/facilitate reconfiguration:
 - Concurrent handler execution (multicore machines).
 - Eliminate unnecessary copies between layers (use pointers)
 - Operation for micro-protocol removing.



2. Self-adaptive protocol (cont'd)

□ P2PSAP protocol architecture



2. Self-adaptive protocol (cont'd)

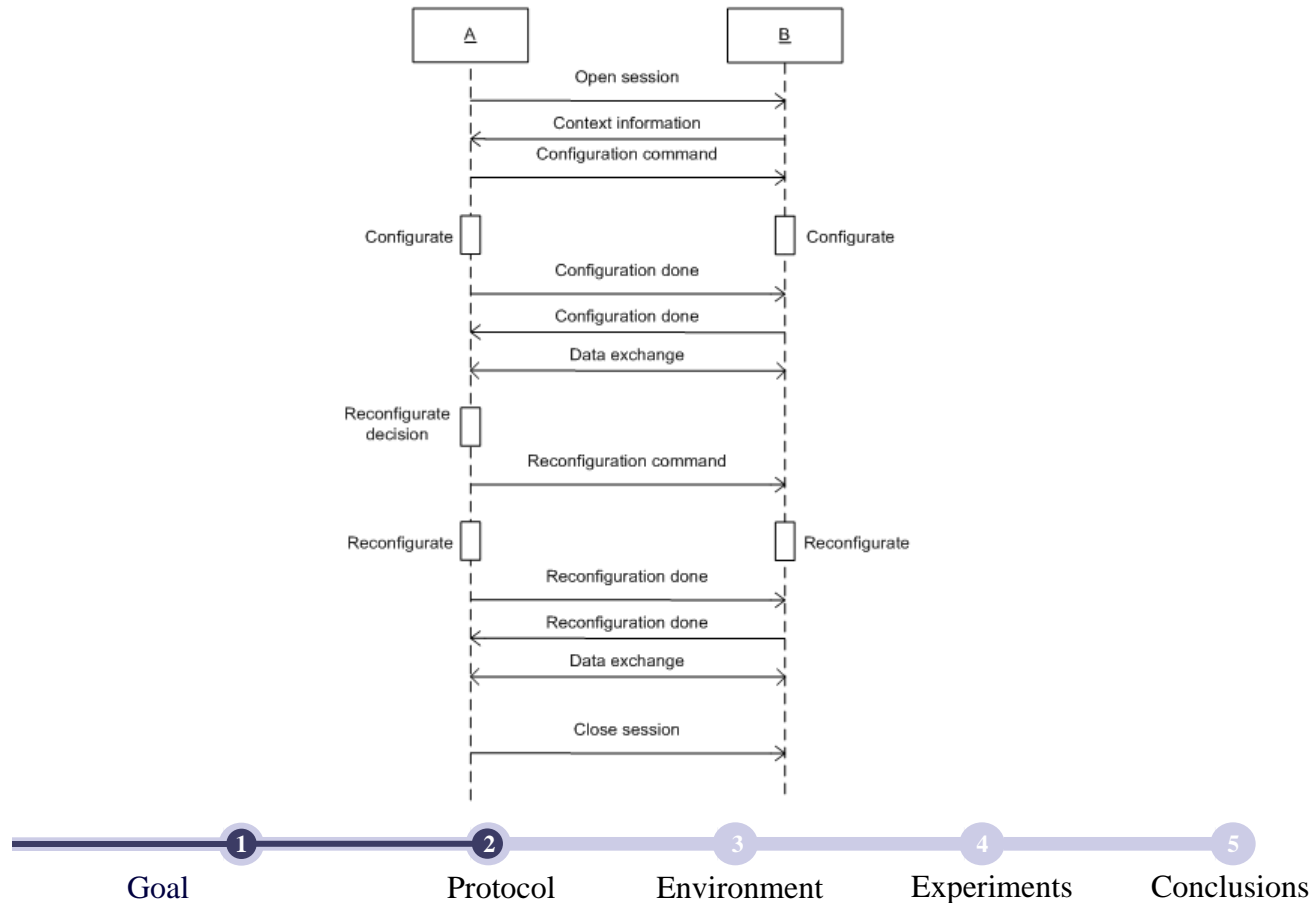
□ Communication adaptation rules

Scheme	Synchronous	Asynchronous	Hybrid
Link			
Intra-cluster	Synchronous Reliable Com.	Asynchronous Reliable Com.	Synchronous Reliable Com.
Inter-cluster	Synchronous Reliable Com.	Asynchronous Unreliable Com.	Asynchronous Unreliable Com.



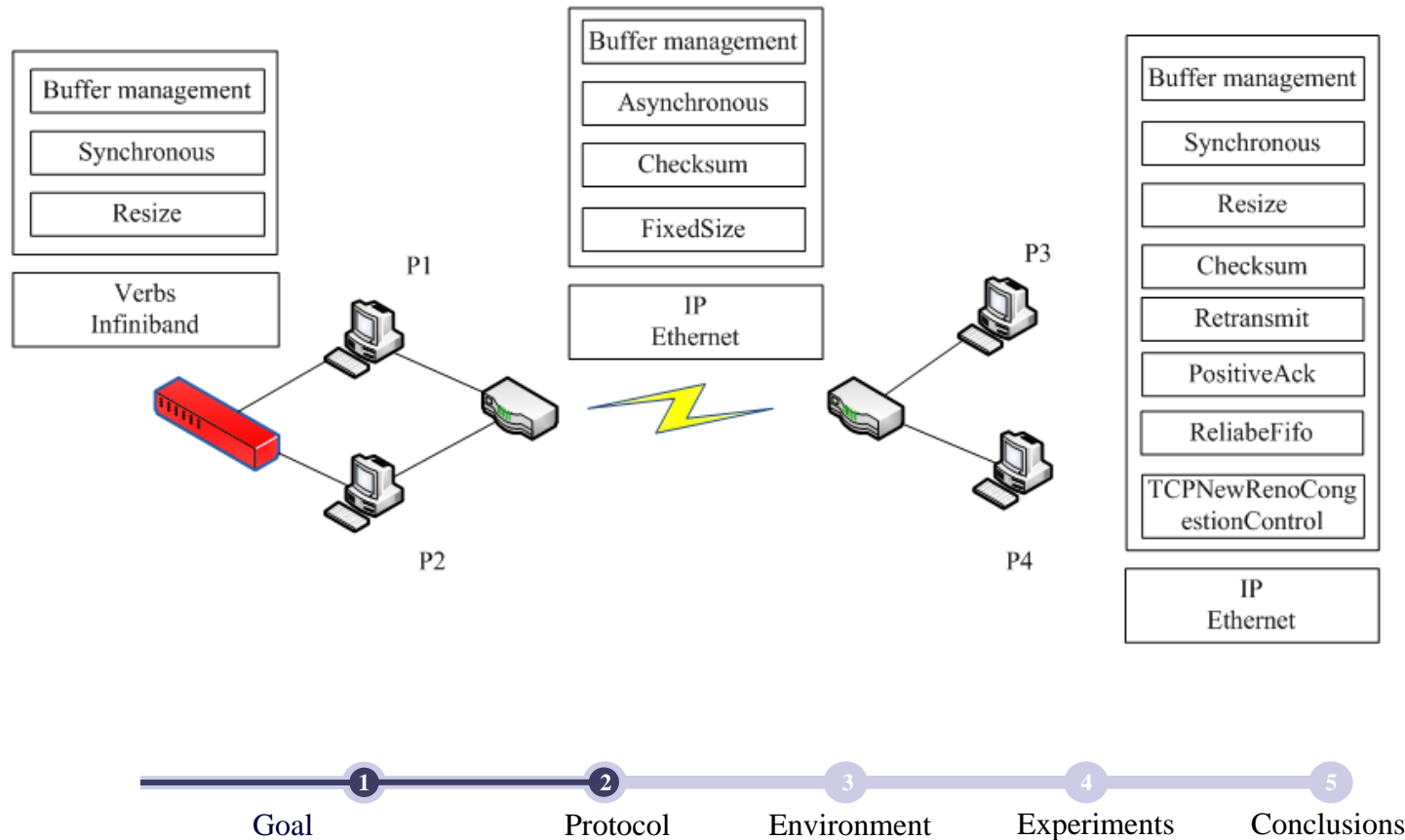
2. Self-adaptive protocol (cont'd)

□ Reconfiguration mechanism



2. Self-adaptive protocol (cont'd)

□ Example of scenario



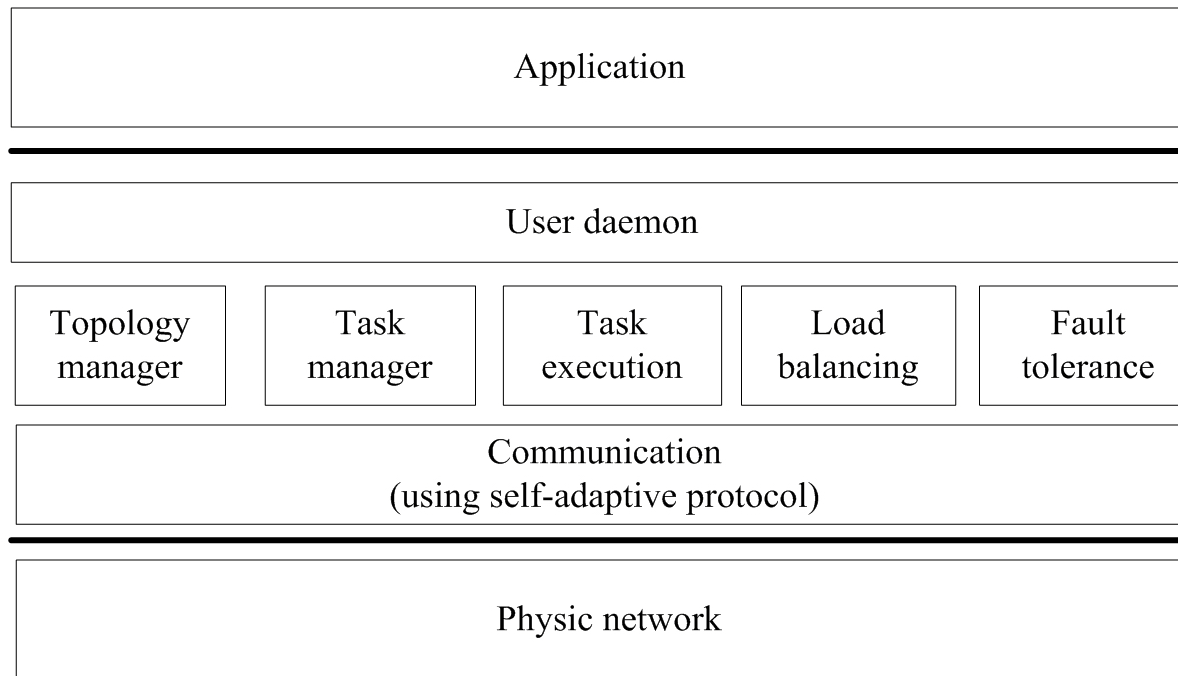
3. Environment

- ❑ Direct communication between peers
- ❑ Reduced set of communication operations:
 - only send and receive operations (P2P_send and P2P_receive).
 - facilitate programming, hide complexity.
- ❑ Communication mode can vary with context:
 - programmer does not select directly a communication mode (programmer can select a scheme of computation).
 - communication mode depends on the context and is determined by the protocol.
 - good efficiency.



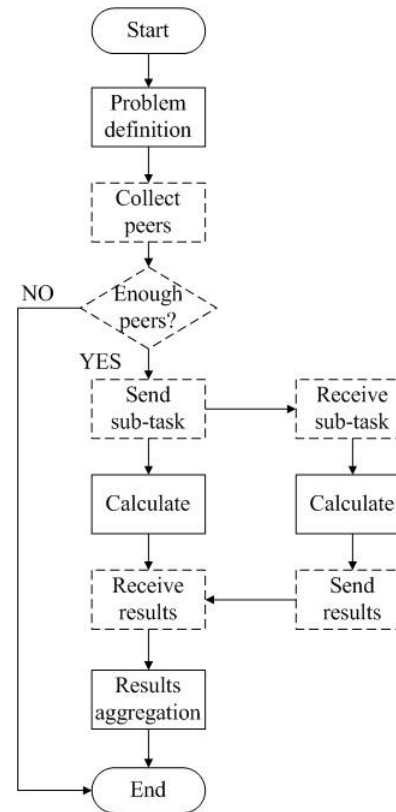
3. Environment (cont'd)

□ P2PDC Environment architecture



3. Environment (cont'd)

□ Application deployment



4. Experiments

□ 3D Obstacle problem

- numerical simulation problems (pde)
- financial mathematics, e.g. option pricing
- mechanics



4. Experiments (cont'd)

□ Fixed point problem:

$$\begin{cases} \text{Find } u^* \in V \text{ such that} \\ u^* = F(u^*), \end{cases}$$

Distributed asynchronous iterative scheme:

$$\begin{cases} u_i^{p+1} = F_{i,\delta} \left(u_1^{\rho_1(p)}, \dots, u_j^{\rho_j(p)}, \dots, u_\alpha^{\rho_\alpha(p)} \right) \text{ if } i \in s(p), \\ u_i^{p+1} = u_i^p \text{ if } i \notin s(p), \end{cases}$$

$$\begin{cases} s(p) \subset \{1, \dots, \alpha\}, s(p) \neq \emptyset, \forall p \in N, \\ \{\{p \in N \mid i \in s(p)\}, \text{ is infinite}, \quad \forall i \in \{1, \dots, \alpha\}, \end{cases}$$

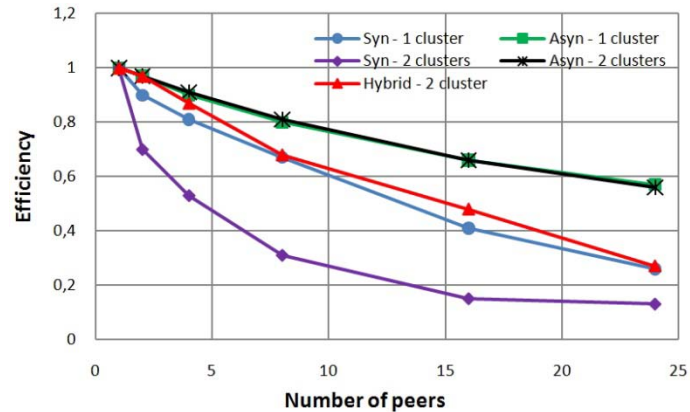
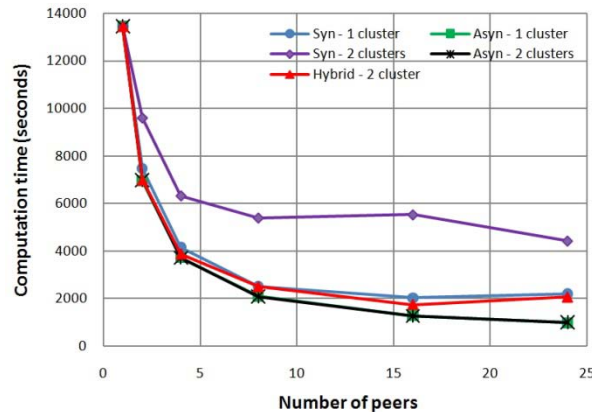
$$\begin{cases} \rho_j(p) \in N, 0 \leq \rho_j(p) \leq p, \forall j \in \{1, \dots, \alpha\}, \forall p \in N, \\ \lim_{p \rightarrow \infty} \rho_j(p) = +\infty, \forall j \in \{1, \dots, \alpha\}. \end{cases}$$



4. Experiments (cont'd)

□ Results

3D obstacle problem, slice decomposition, 3,000,000 variables, NICTA testbed, Sidney.



5. Conclusions

- ❑ Self-adaptive protocol P2PSAP for P2P HPC
- ❑ Current version of environment P2Pdc
- ❑ Experiments on NICTA and Grid 5000 testbeds for obstacle problem.
- Decentralised functions of P2PDC.
- Improvements: code, protocol, environment.
- Applications: process engineering, logistics.
- Other testbeds PlanetLab (GENI).
- Self-organization → efficiency & everlastingness.

